

1. Is the matrix $A^T A$ positive semi-definite? (hint, for $A^T A$ to be positive semi-definite, $x^T A^T A x \geq 0$ for all x .)

- (a) yes
- (b) no

2. Is the following linear system controllable?

$$x_{k+1} = \begin{bmatrix} 1 & 3 \\ -2 & 0 \end{bmatrix} x_k + \begin{bmatrix} 0 \\ .1 \end{bmatrix} u_k \quad (1)$$

- (a) yes
- (b) no

3. Below is a finite-horizon LQR problem,

$$\min_{x_{1:N}, u_{1:N-1}} \sum_{i=1}^{N-1} \left[\frac{1}{2} x_i^T Q x_i + \frac{1}{2} u_i^T R u_i \right] + \frac{1}{2} x_N^T Q_f x_N \quad (2)$$

$$\text{st } x_1 = x_{1C}, \quad (3)$$

$$x_{i+1} = A x_i + B u_i \quad \text{for } i = 1, 2, \dots, N-1, \quad (4)$$

where $Q \succeq 0$, $R \succ 0$, and $[A, B]$ is controllable. We can solve this problem with either convex optimization that solves for (x, u) directly, or a Ricatti recursion that solves for an optimal policy $u_i = -K_i x_i$. Will these two solutions be equivalent?

- (a) yes
- (b) no

4. If we modify the finite-horizon LQR problem to incorporate bound constraints on the controls, we get the following problem:

$$\min_{x_{1:N}, u_{1:N-1}} \sum_{i=1}^{N-1} \left[\frac{1}{2} x_i^T Q x_i + \frac{1}{2} u_i^T R u_i \right] + \frac{1}{2} x_N^T Q_f x_N \quad (5)$$

$$\text{st } x_1 = x_{1C}, \quad (6)$$

$$x_{i+1} = A x_i + B u_i \quad \text{for } i = 1, 2, \dots, N-1, \quad (7)$$

$$u_{min} \leq u_i \leq u_{max} \quad \text{for } i = 1, 2, \dots, N-1. \quad (8)$$

If we take the Ricatti solution ($K_{1:N-1}$) from the original finite-horizon LQR problem, and apply the following policy:

$$u_i = \max(u_{min}, \min(-K_i x_i, u_{max})). \quad (9)$$

Will we recover a solution to the new optimization problem? You should think about the theory as well as implementing it yourself and trying. First figure out what $\max(a, \min(u, b))$ does when $a < b$, making sure to use $\max()$ and $\min()$ if you're doing this in Julia.

- (a) yes
- (b) no

5. Which of the following cost functions are convex in $x \in \mathbb{R}^N$? ($Q \succ 0$)

- (a) $c^T x$
- (b) $-c^T x$
- (c) $\sum_i x_i$
- (d) $\|x\|_1$
- (e) $\|x\|_2$
- (f) $\|x\|_2^2$
- (g) $\|Ax - b\|_1$
- (h) $x^T Q x$
- (i) $(Ax - b)^T Q (Ax - b)$

6. Which of the following constraints are convex in $x \in \mathbb{R}^N$? ($Q \succ 0$)

- (a) $Ax = b$
- (b) $Ax \leq b$
- (c) $\|x\|_2 \geq 3$
- (d) $\|Ax - b\|_1 \leq 3$
- (e) $\|Ax - b\|_2 \leq 3$
- (f) $\|Ax - b\|_2 = 3$
- (g) $\|x\|_2^2 \leq 3$
- (h) $x^T Q x \leq 3$
- (i) $x^T Q x = 3$
- (j) $x^T Q x \geq 3$
- (k) $x^T Q x + q^T x \leq 3$